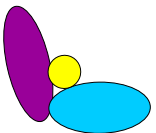
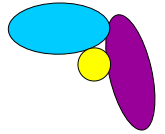


THE DISCRETE ELEMENT METHOD

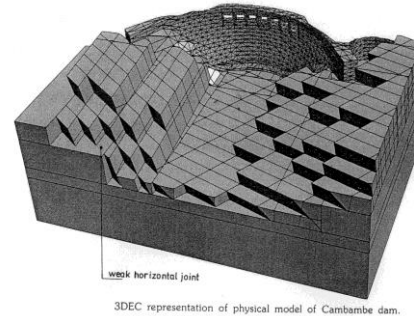
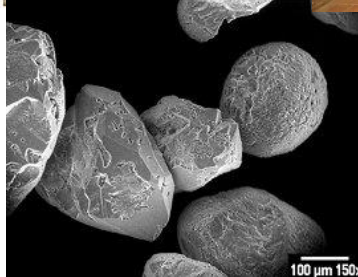
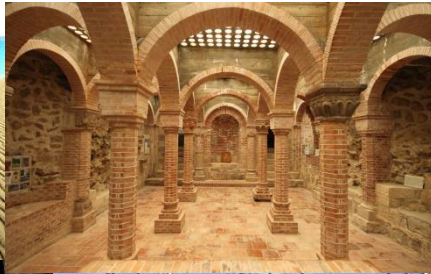


WHAT IS DEM?



The aim to model materials or structures having discrete internal builtup

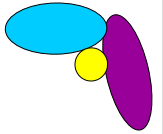
„what does it do if loads are put on it?”



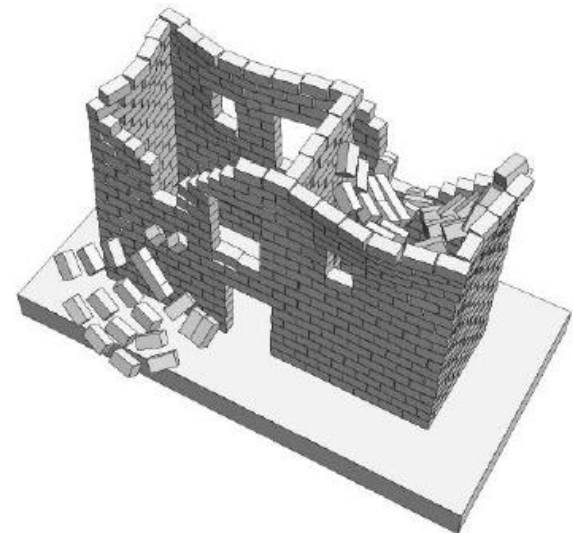
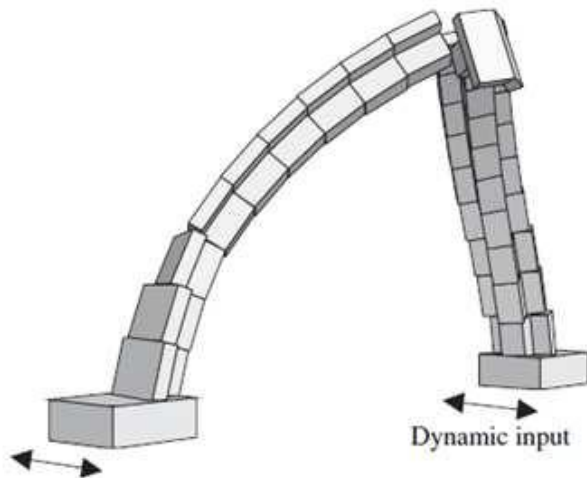
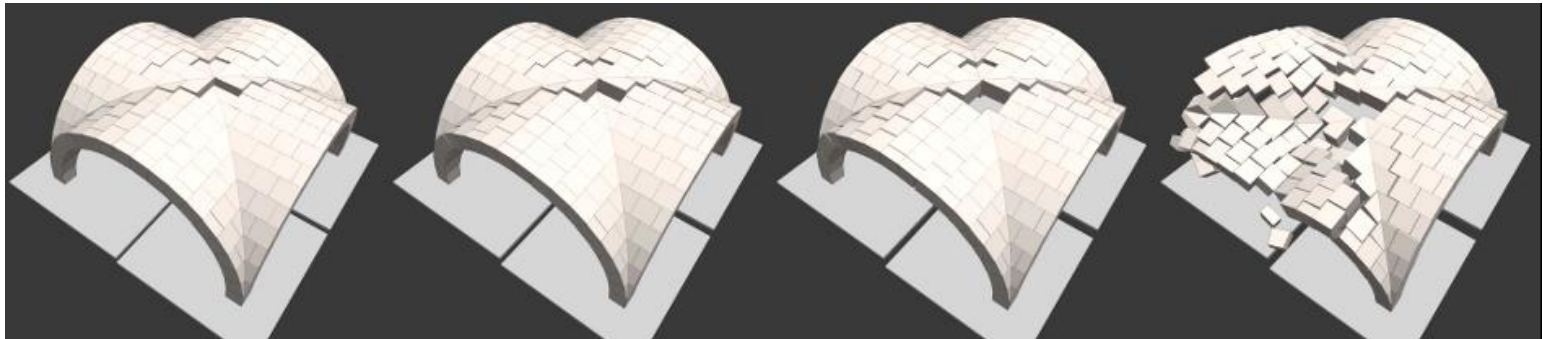
This presentation:

- phenomena which are not properly reflected by continuum modelling
- the definition of Discrete Element Modelling
- the main steps of Discrete Element Modelling

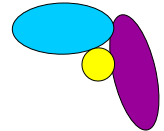
NON-CONTINUOUS PHENOMENA



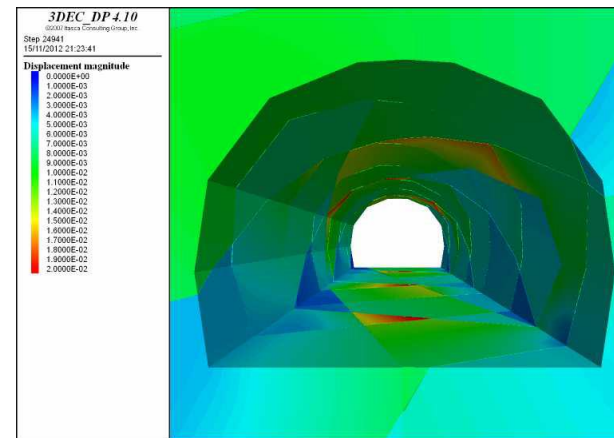
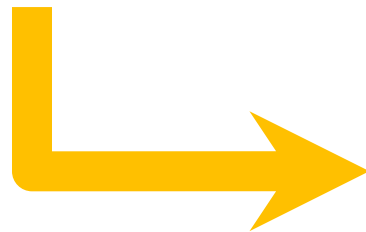
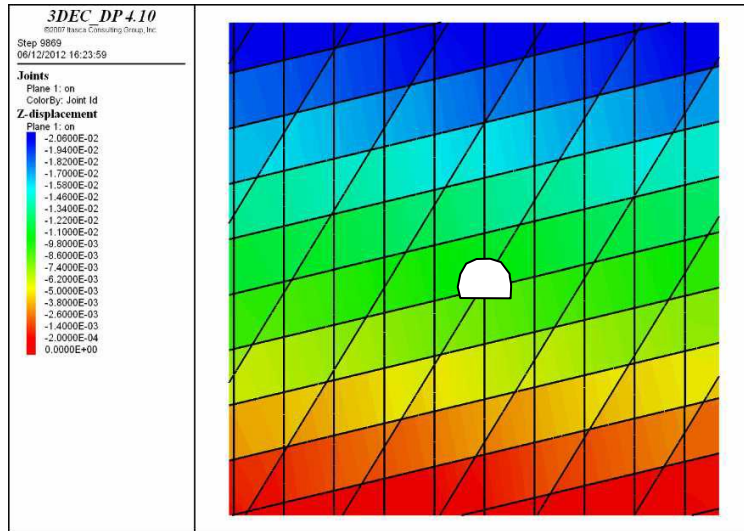
Collapse of masonry structures:



NON-CONTINUOUS PHENOMENA



Tunnels in fractured rock soils:



D. Borbély, MSc Thesis

NON-CONTINUOUS PHENOMENA

Silos:

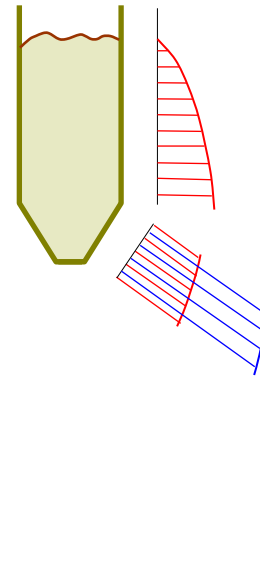


problems e.g.:

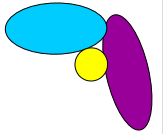
→ Pressure acting on the walls?

→ Emptying: sudden large forces

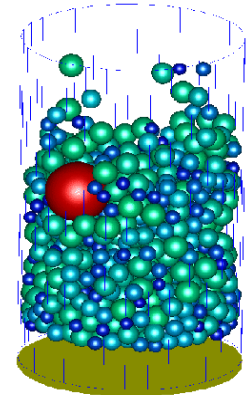
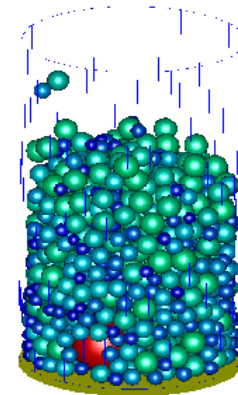
→ arching ☹️



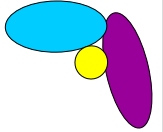
NON-CONTINUOUS PHENOMENA



Segregation: „Brasil nut effect”

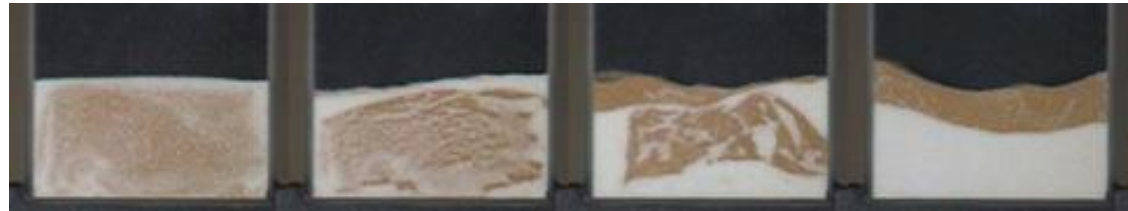
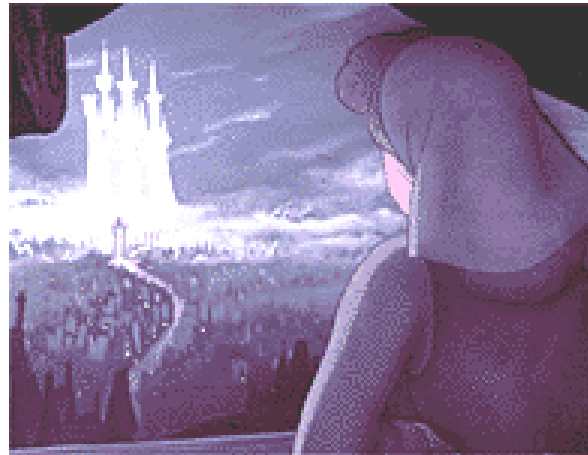


NON-CONTINUOUS PHENOMENA



Segregation:

useful application:

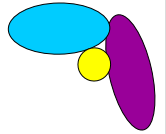


when harmful:

e.g. pharmaceutical industry

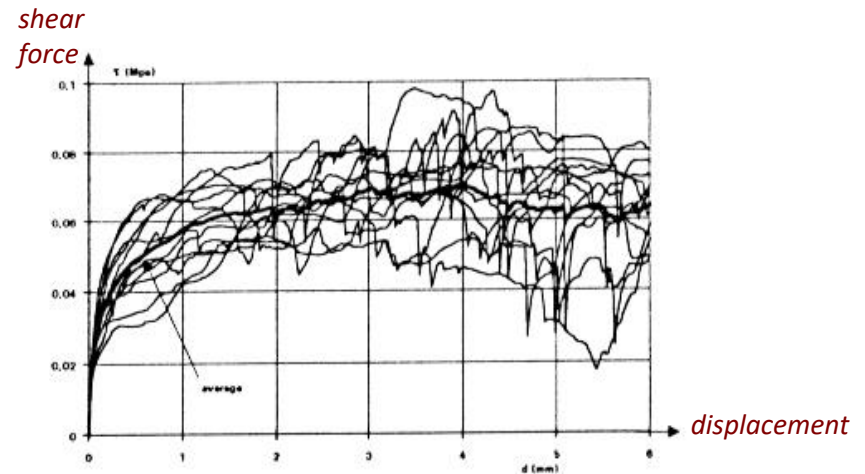
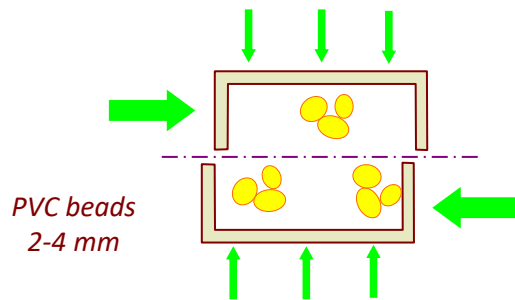
Microstructural explanation: ????

NON-CONTINUOUS PHENOMENA

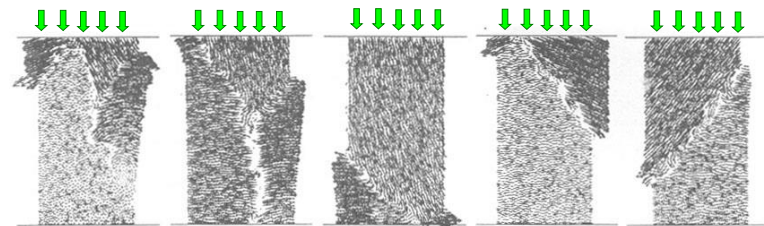


Soil mechanics:

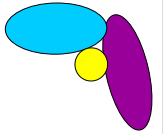
e.g. Large scatter in the measured data:



also for cemented materials!



NON-CONTINUOUS PHENOMENA



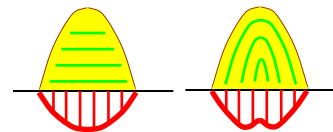
Soil mechanics:

e.g. Stress dip under sand piles:

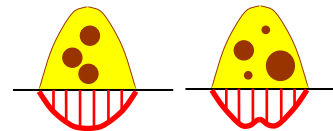


depends on:

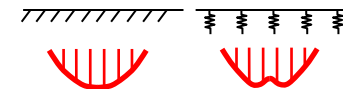
→ deposition technique



→ grain size distribution

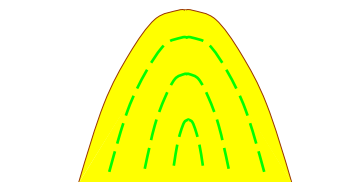


→ stiffness of the subsoil

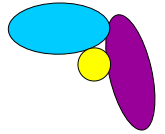


Microstructural explanation:

„internal arches”



NON-CONTINUOUS PHENOMENA



Microgravity environment:

e.g. earthquakes:

$$\cancel{g = 9.81 \text{ m/sec}^2} \Rightarrow$$



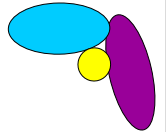
San Francisco, 1989

project question:

How granular assemblies behave under nearly-zero gravity?

NASA, 1996; 1998; [2003]

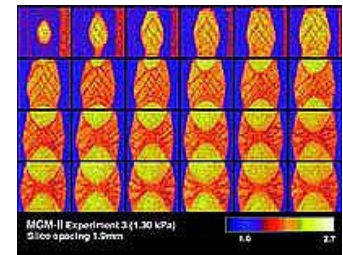
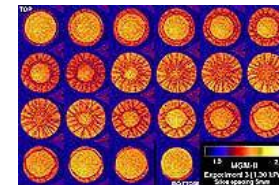
NON-CONTINUOUS PHENOMENA



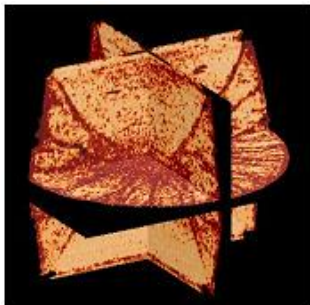
Microgravity environment:



- very low confining pressure
- triaxial compression procedures
- until different stress levels
- fixed with thin resin
- after coming home: CT



The 3D microstructure during the process:



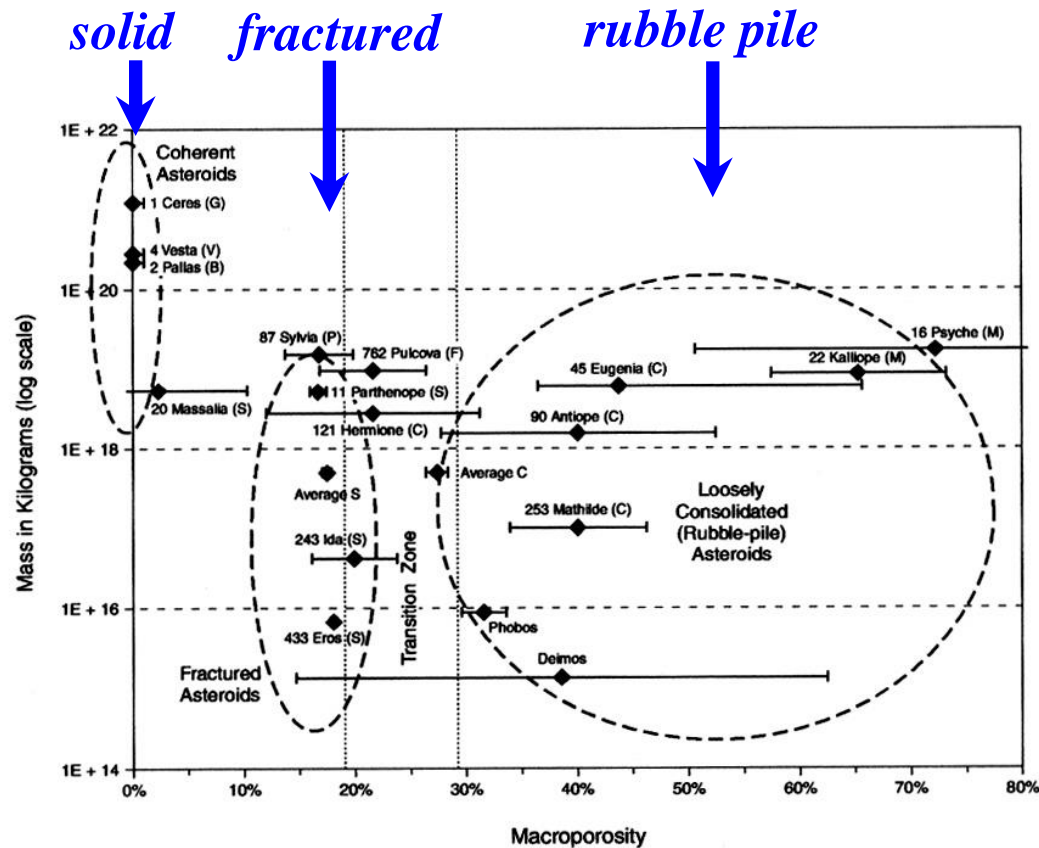
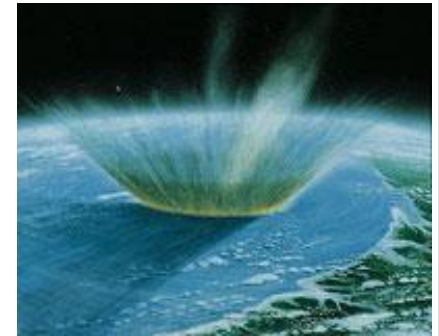
Theoretical results:

extremely complicated continuum models

NON-CONTINUOUS PHENOMENA

Microgravity environment:

e.g. modelling of „rubble pile”-asteroids:

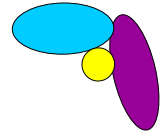


„rubble-pile”-type:

porosity > 30%

*e.g. Tunguska event (?),
1908, Siberia*

NON-CONTINUOUS PHENOMENA

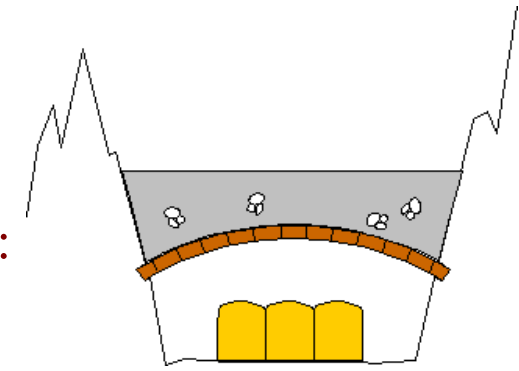


The surface of the Moon:

AS17-134-20503

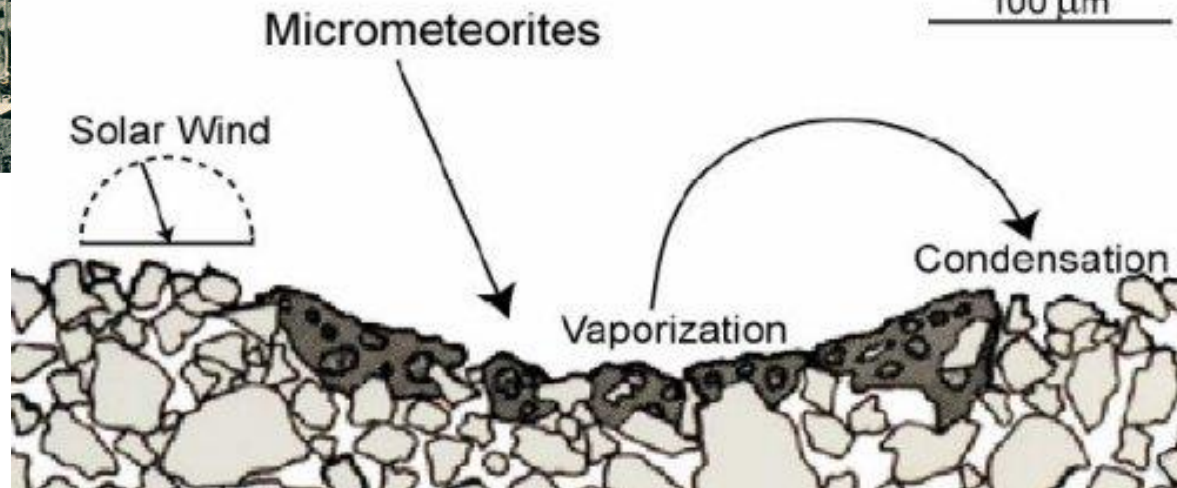


use it for
protection:

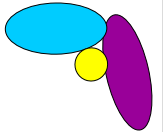


100 μm

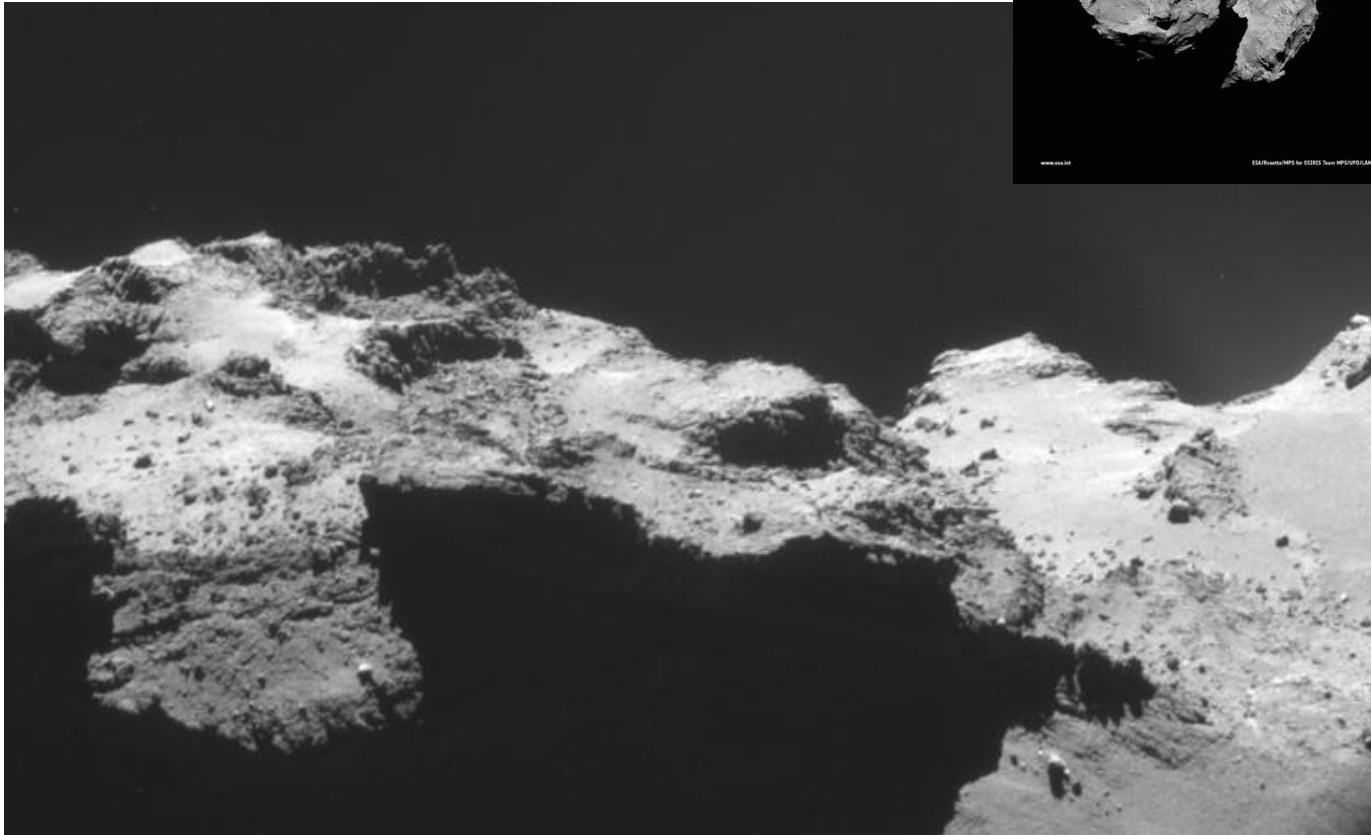
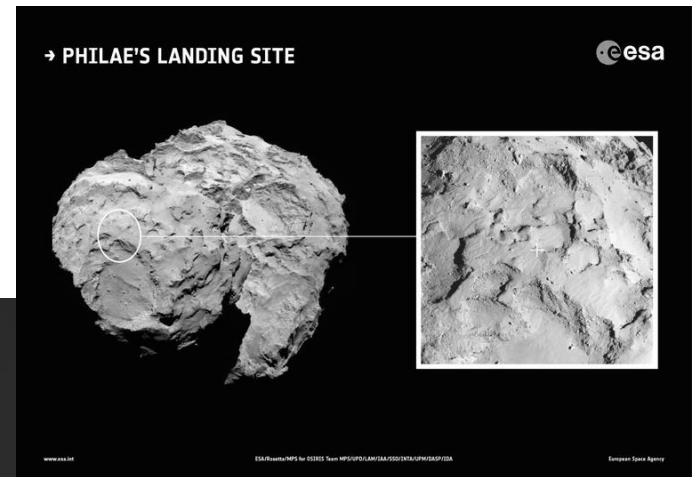
„regolith”:



NON-CONTINUOUS PHENOMENA

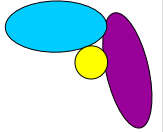


Landing on a comet:



← Churyumov – Gerasimenko

WHAT IS DEM?



The aim: to model materials or structures having discrete internal builtup

„what does it do if loads are put on it?”

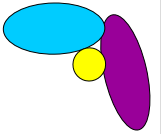
*„There are no good continuum models,
only good curve fits.”*

/unknown soil mechanical
from the XXth century/

This presentation:

- phenomena which are not properly reflected by continuum modelling
- the definition of Discrete Element Modelling
- the main steps of Discrete Element Modelling

WHAT IS DEM?

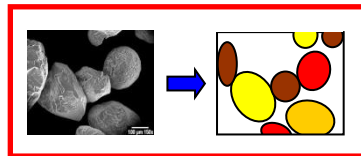
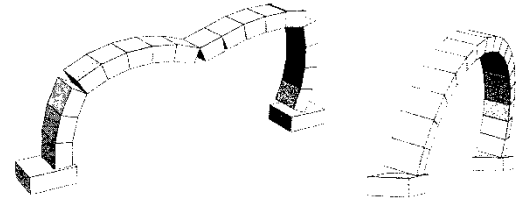


The aim: to model materials or structures having discrete internal builtup

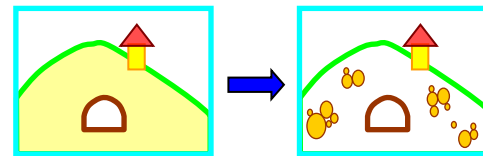
„what does it do if loads are put on it?”

The components of the model:

separate elements + their contacts



or



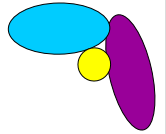
mechanical models for the material of the elements: → rigid
→ deformable

contacts → recognition
→ mechanical models for the contacts:

→ non-deformable

→ deformable: e.g. point-like, deformable } e.g. frictional,
e.g. finite size, deformable } e.g. cemented

WHAT IS DEM?

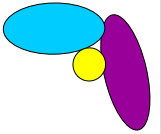


Definition:

A discrete element model is a numerical model which satisfies the following conditions:

- consists of clearly separated elements and contacts between them;
- the elements have their own independent degrees of freedom
e.g. translational, rotational, deformational
(→← FEM: „C0-continuous”, „C1-continuous”)
- the displacements are finite,
- elements can be separated and new contacts can be formed between them,
so that the creation of new contacts are automatically recognised
(→← frame models, FEM fracture models: no new contacts)

WHAT IS DEM?



History overview

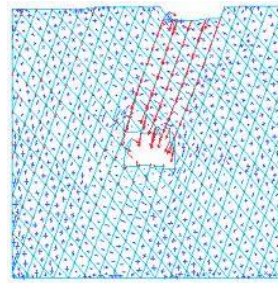
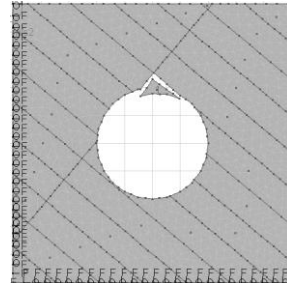
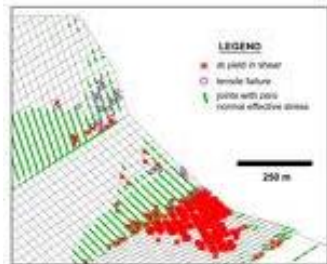
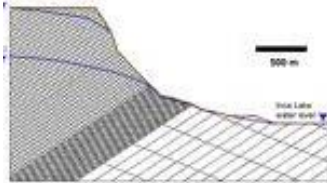
→ end of 1960ies:



Peter A Cundall,
Imperial College:

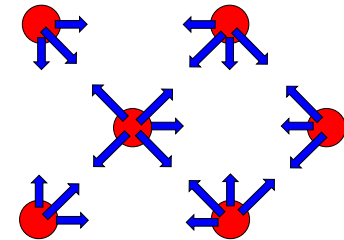
UDEC

(„Uniform Distinct Element Code”)

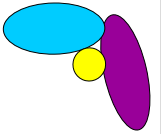


model for fractured rocks

→ 1970ies: Molecular Dynamics methods, physics literature
not really DEM



WHAT IS DEM?



History overview

→ end of 1970ies: Cundall & Strack, 1979:

BALL

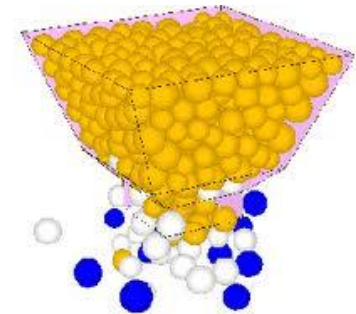
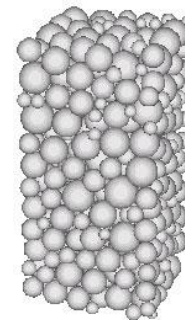
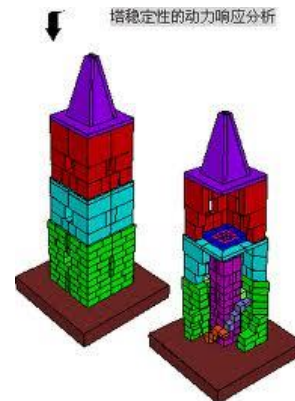
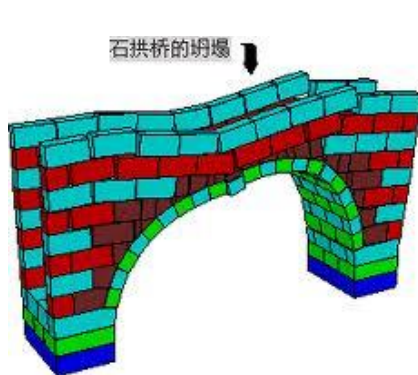
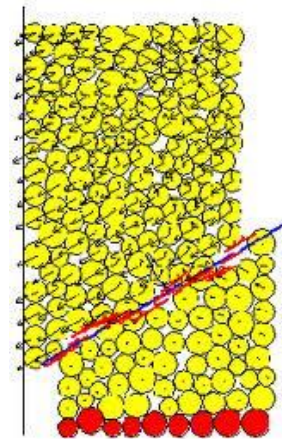
→ from the 1980ies:

→ several new codes, already in 3D

→ general element shapes

→ different mathematical tools

→ from the 1990ies: practical applications in engineering



EXAMPLE

1. Define the geometry:

ball id 1 x 0.10 y 0.20 rad 0.10

ball id 2 x 0.55 y 0.20 rad 0.15

ball id 3 x 0.30 y 0.40 rad 0.15

wall id 1 nodes 0.0 0.0 0.7 0.0

wall id 2 nodes 0.7 0.0 0.7 0.5

wall id 3 nodes 0.0 0.5 0.0 0.0

2. Specify the material parameters:

property density 10.0

property kn 1.e4 ks 0.5e4 friction 0.2

wall id 1 kn 1.e12 ks 0. friction 0.

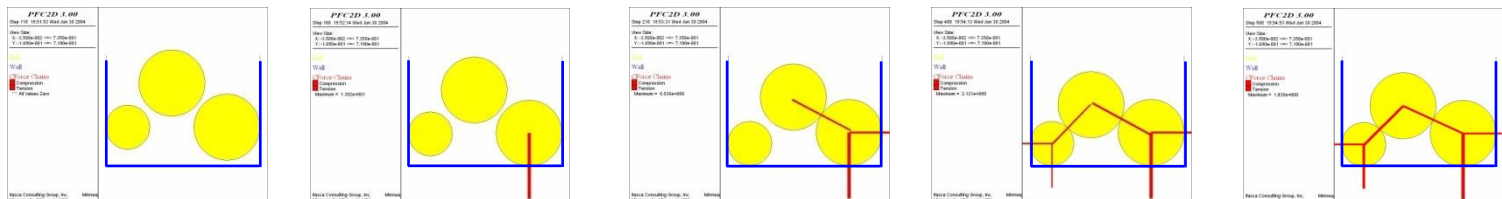
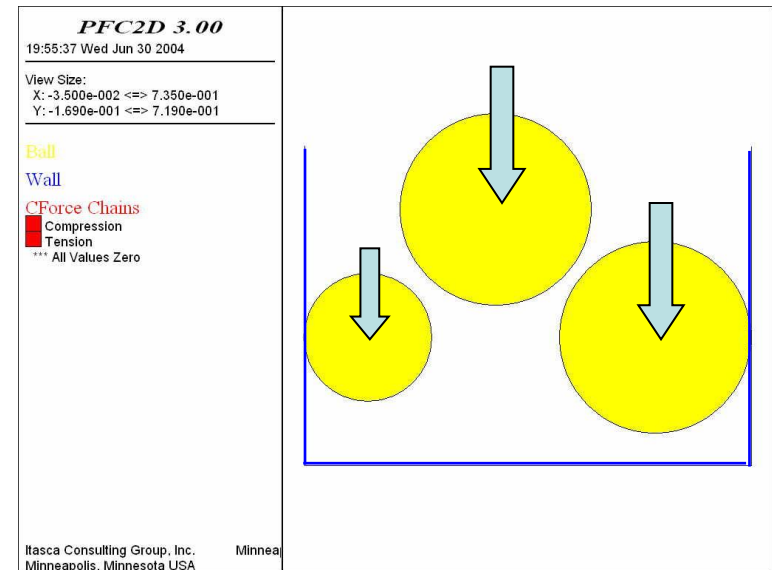
wall id 2 kn 1.e12 ks 0. friction 0.

wall id 3 kn 1.e12 ks 0. friction 0.

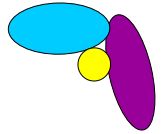
3. Specify the loads:

set gravity 0.0 -9.81

4. Calculate the displacements [series of small increments]



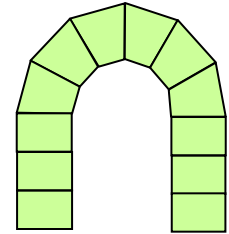
WHAT IS DEM?



Main steps of the analysis of an engineering problem:

- the model: collection of separate elements('discrete elements')
{1 body \leftrightarrow 1 element} or {several bodies \leftrightarrow few elements}

Step 1.: define the initial geometry

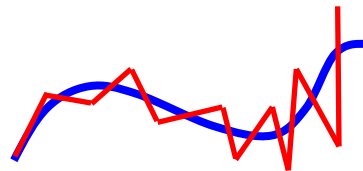


- rigid or deformable *elements*; rigid or deformable *contacts*

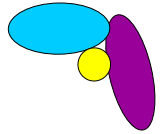
Step 2.: specify the material characteristics

- the loading process:
(e.g. external forces acting on the elements; e.g. prescribed displacements)
- calculation of the state changing: *series of small increments, based on „ $\mathbf{f} = m\mathbf{a}$ ”*

Step 3.: calculation of the actual displacement increments



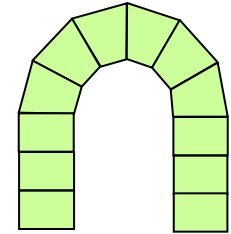
WHAT IS DEM?



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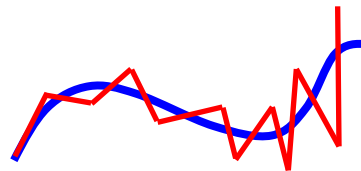


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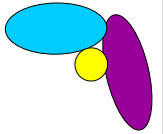
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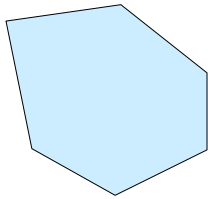
Step 3.: calculation of the actual displacement increments



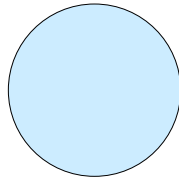
THE GEOMETRY



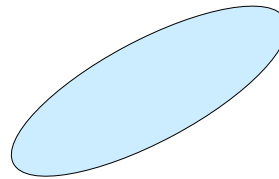
Element shapes:



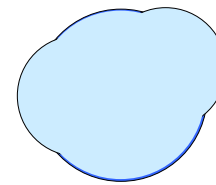
polygon, polihedron



circle, sphere



ellipse, ellipsoid

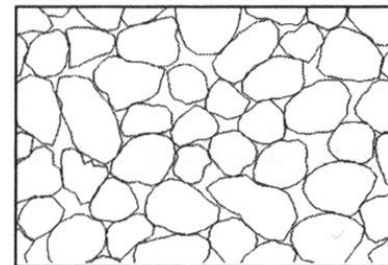
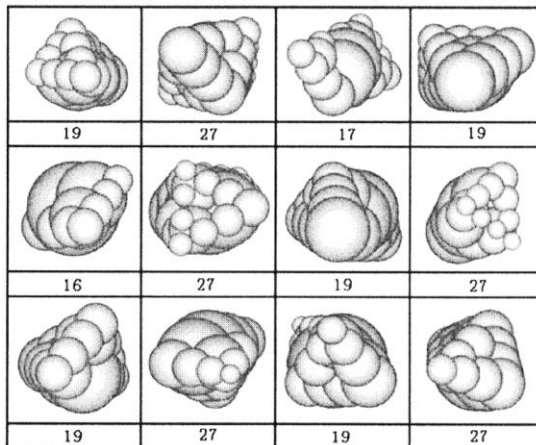


complex shapes

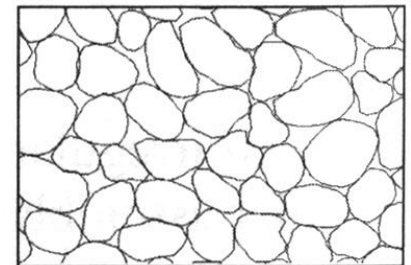
Matsushima, 2005:

e.g. Lu & McDowell, 2007, PFC-3D:

Railway ballast

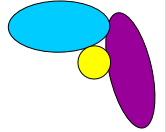


(a) Toyoura sand model

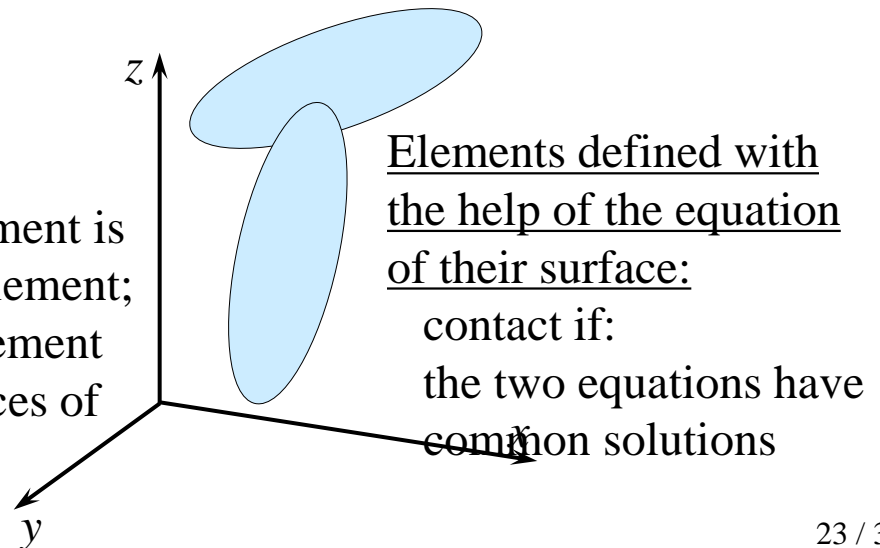
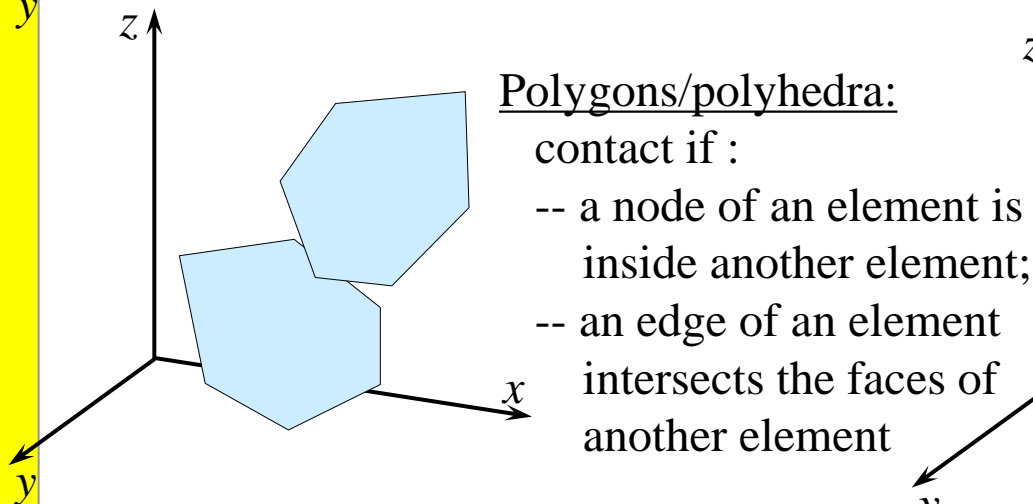
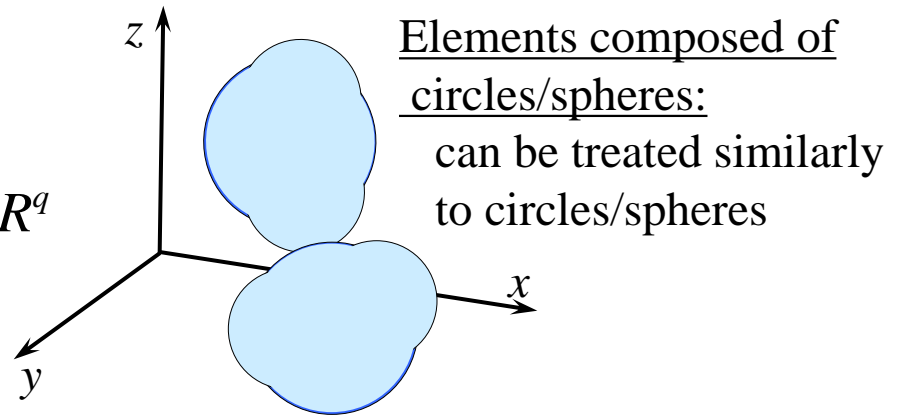
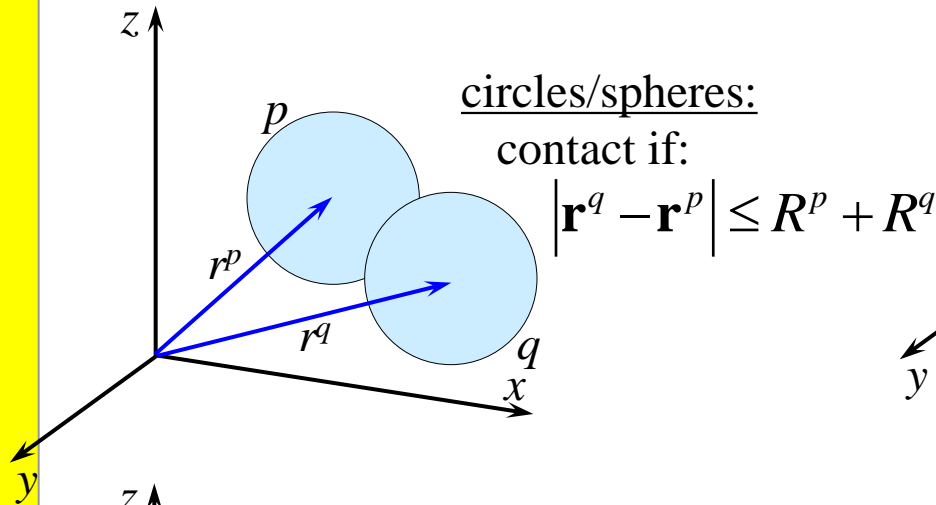


(b) Ottawa sand model

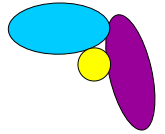
THE GEOMETRY



Contact recognition: a point of an element is in the interior of another element



THE GEOMETRY

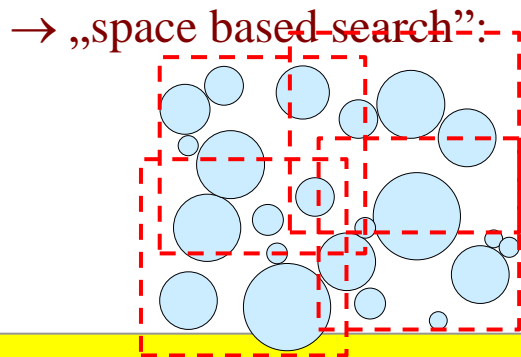
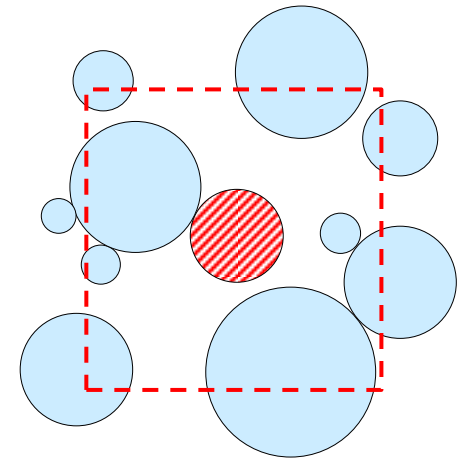


Contact recognition: several different algorithms exist;
its speed basically determines the computational
efficiency of the whole DEM code!

the time consuming part: to check the existence of a contact with exact calculations

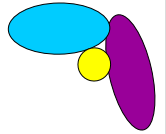
Trick #1:
avoid checking every element with every other element:

→ „body based search” technique:
consider only those others which are in the
vicinity of the analyzed element;
then take the next element to analyze, ...



divide the domain into „windows” (overlapping);
collect which elements are in which windows;
analyze those pairs only where both elements
belong to the same window

THE GEOMETRY

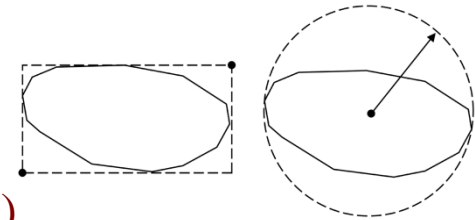


Contact recognition: several different algorithms exist;
its speed basically determines the computational
efficiency of the whole DEM code!

the time consuming part: to check the existence of a contact with exact calculations

Trick #2:

Simple surrounding domains checked first
(instead of the elements having complicated shapes)

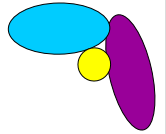


the idea: „surrounding domain” assigned to each element
(simple shape: brick; sphere)

→ Phase 1.: intersection between the surrounding domains? (fast)

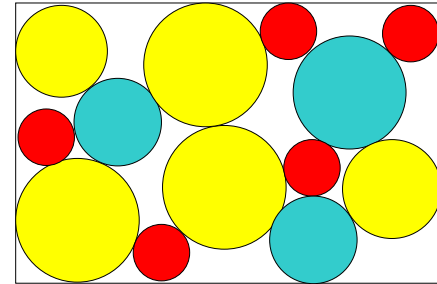
→ if necessary: Phase 2.: detailed, exact calculations (slow)

THE GEOMETRY



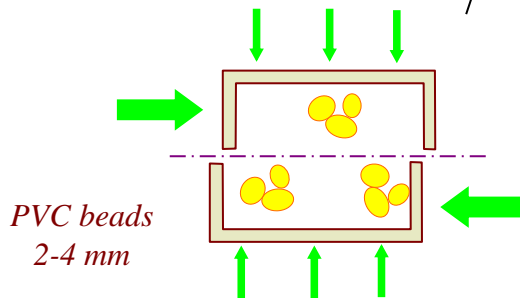
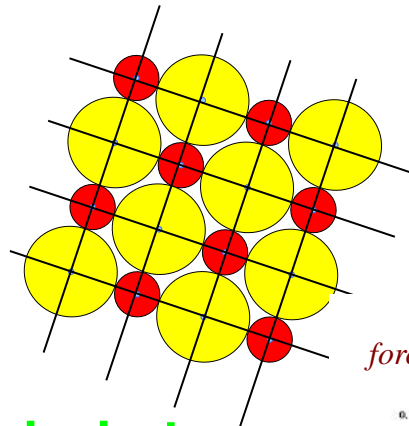
Common problem often faced:

Prepare an initial arrangement
so that the elements touch each other!

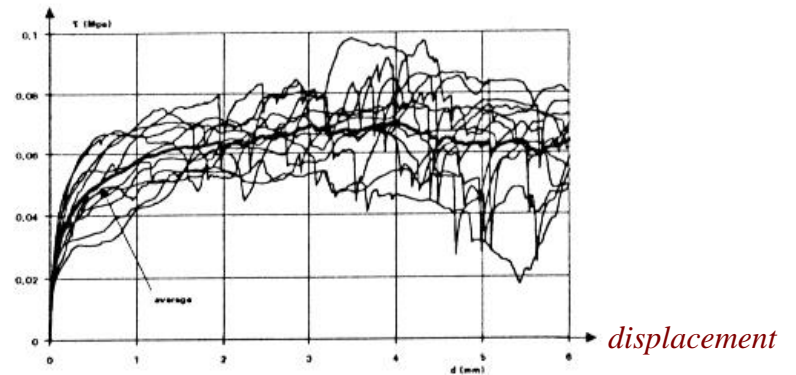


→ Regular arrangements:

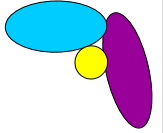
unrealistic
mechanical
behaviour!



force

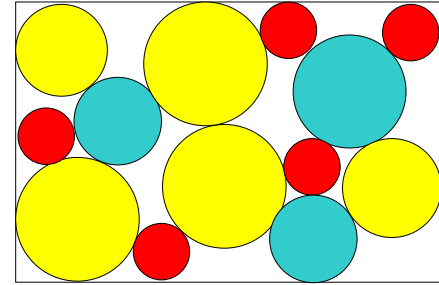


THE GEOMETRY



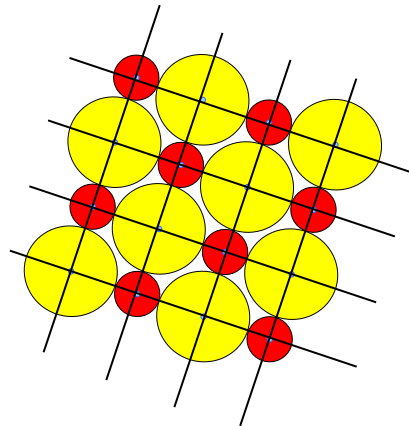
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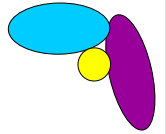
→ Regular arrangements:

unrealistic
mechanical
behaviour!



→ Dynamic techniques
→ Constructive techniques

THE GEOMETRY

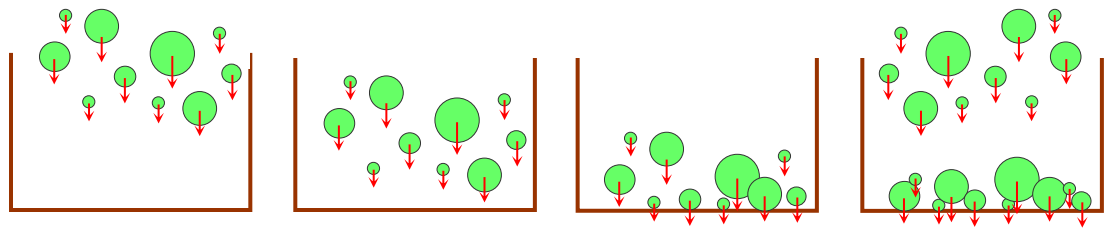


Common problem often faced:

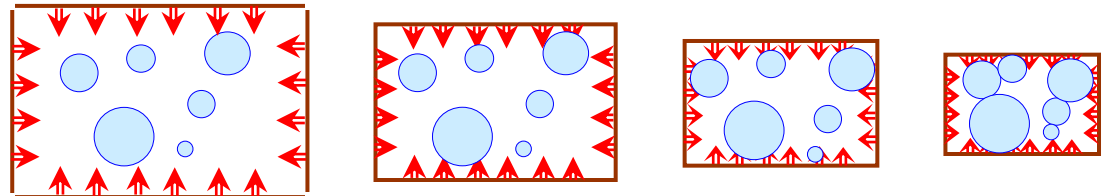
Prepare an initial arrangement
so that the elements touch each other!

→ Dynamic techniques: apply the DEM code itself!

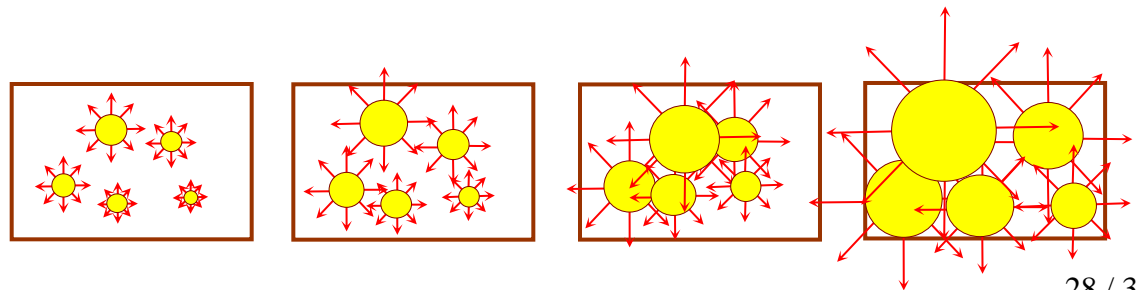
e.g. gravity
deposition:



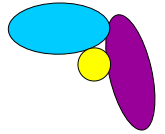
e.g. isotropic
compression:



e.g. grow the elements
into the domain
as a container:



THE GEOMETRY

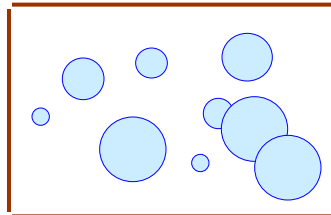


Common problem often faced:

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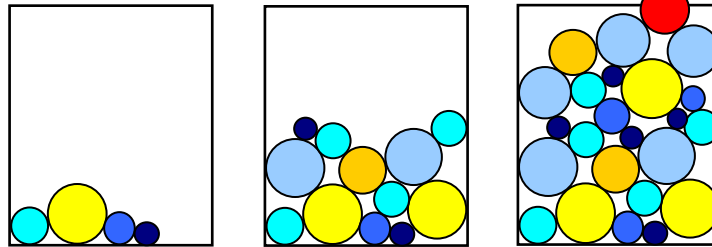
→ Constructive techniques: purely geometric calculations!

e.g. SSI:
„Simple
Sequential
Inhibition”

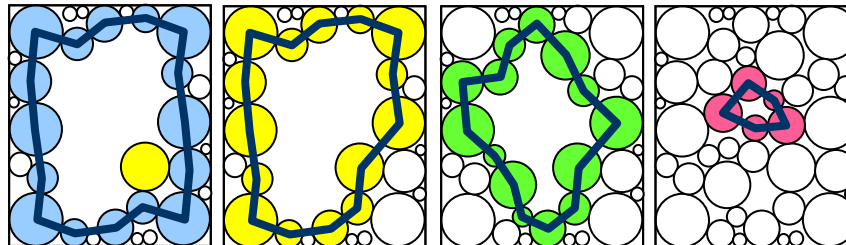


then dynamic densification is needed!

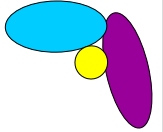
e.g. „sedimentation”
techniques:



e.g. Inwards
Packing:

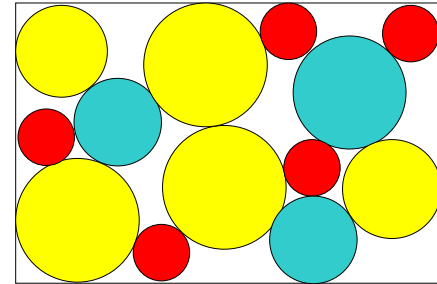


THE GEOMETRY



Common problem often faced:

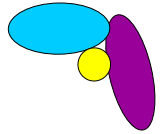
Prepare an initial arrangement
so that the elements touch each other!



Summary:

- Regular arrangements:
unrealistic results
- Dynamic techniques:
slow, but easy to use
- Constructive techniques:
very fast, but no commercial codes available at the moment

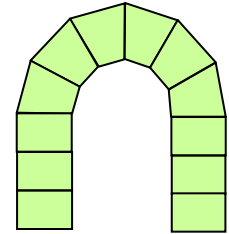
WHAT IS DEM?



Main steps of the analysis of an engineering problem:

- the model: collection of separate elements('discrete elements')
{1 body \leftrightarrow 1 element} or {several bodies \leftrightarrow few elements}

Step 1.: define the initial geometry



- rigid or deformable *elements*; rigid or deformable *contacts*

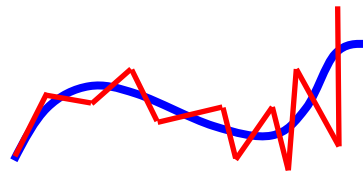
Step 2.: specify the material characteristics

- the loading process:

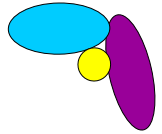
(e.g. external forces acting on the elements; e.g. prescribed displacements)

- calculation of the state changing: *series of small increments, based on „ $\mathbf{f} = m\mathbf{a}$ ”*

Step 3.: calculation of the actual displacement increments



MECHANICAL PROPERTIES



Mechanical behaviour of the elements:

role: to specify how to calculate the stresses from the deformations of the elements

→ perfectly rigid elements: deformability concentrated into the contacts

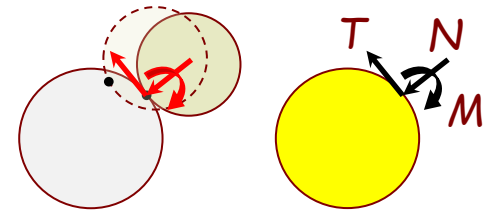
→ deformable elements:

stress-strain-relations have to be specified

[e.g. E , μ , ...]

Mechanical behaviour of the contacts:

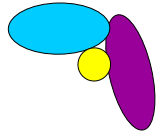
role: to specify how to calculate the contact forces from the relative displacements at the contact



→ usually: „deformable” contacts (relative displ. at the contact regions)

→ sometimes: infinitely rigid contacts: no overlap or any other deformation

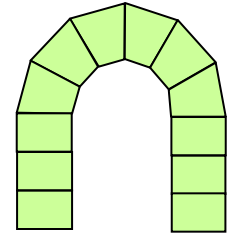
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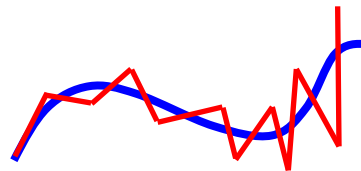
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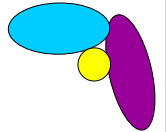
- the loading process:
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- calculation of the state changing: *series of small increments, based on „ f = ma ”*

Step 3.: calculation of the actual displacement increments



QUESTIONS



1. What are the conditions to consider a numerical technique a discrete element model?
2. What is the role of the constitutive relations of the elements? From the point of view of mechanical behaviour, what basic types of elements are used in the different DEM models?
3. What is the role of the constitutive relations of the contacts? From the point of view of mechanical behaviour, what basic types of contacts are used in the different DEM models?
4. How can we prepare an initial arrangement of touching elements? What is the difference between dynamic, constructive and collective rearrangement techniques?
5. Introduce the aim and the basic idea of the body-based technique! Introduce the aim and the basic idea of the space-based technique!
6. What are the basic steps of discrete element modelling?